

## LINEAR GANTRY **RLP600**

#### FOR ENHANCED QUALITY AND PRODUCTIVITY IN LARGE-SCALE WORKSPACES

In its maximum configuration, the **RLP600 linear gantry robot** has three cartesian axes and three rotary axes, which are fully synchronized and interpolated servo axes controlled by the robot controller. The double-sided bearing of the first axis ensures maximum dynamics with very high stability.

The experience gained from a large number of installed handling applications and our expertise as one of the leading providers of intelligent automation solutions for more than five decades have been incorporated into the development of the new **RLP600**.

#### **YOUR BENEFITS**

- combined with the very low interference contours of the robot kinematics, this is ideal for interlinking work sequences for loading and unloading, but also for palletizing or transferring
- modular design with workspaces from 16 m<sup>3</sup> to 1,069 m<sup>3</sup> make the RLP600 a safe investment for your automation system
- state-of-the-art servo drive technologies are used to achieve the best possible dynamics, performance and reliability



#### SCOPE OF SUPPLY INCLUDING

- RLP600 with flexible stroke and staggered operating height Basic stroke:
  - A1 = 4,000 mm,
  - A2 = 4,000 mm,
  - A3 = 1,000 mm

#### **OPTIONS**

- Wrist axle modules
- Incremental stroke lengths A1 – A3
- Incremental height adjustment of the support columns
- Redundant holding brake A3
- Central lubrication system
- Energy supply
- Adapted to customer specifications
- Extra seals for guiding systems

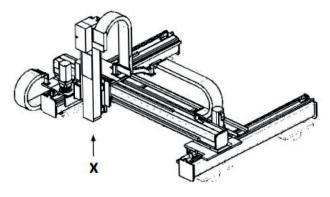




### LINEAR GANTRY RLP600

#### **Technical data**

Nominal payload capacity	kg	600
Payload range (depending on stroke A3)	kg	525 to tbd
Repeat positioning accuracy	mm	±0.8
Number of axes		3
Work envelope	m³	16 to 1,069
Medium power consumption	kVA	7.5
Connected load	kVA	11.7
Weight of basic stroke A1 – A3 (without support columns, without load)	kg	tbd



Gravty centre of total mass observe max. tilting moment

#### Velocities

A1	m/s	2
A2	m/s	2
A3	m/s	1.3

Strokes		A1	A2	A3
Basic stroke	mm	4,000	4,000	1,000
Max. stroke	mm	45,000	9,500	2,500
Extension steps	mm	1,000	500	250
Extra weight for each upgrade	kg	tbd	tbd	tbd

#### Support column

Basic size	mm	450
Basic height	mm	1,750
Maximum height	mm	3,000
Height of extension steps	mm	250
Support column spacing (max.)	mm	5,000
Support arm projection (max.)	mm	1,250

#### Table Maximum load A3

Stroke lengths A3 [mm]	Load (max.)	
2,500	kg	525

#### Max. lever arm with max. load

L <sub>z</sub>	mm	500		
Max. tilting moment				

M A3 Nm	2,000
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For further information please contact us under: sales@reisrobotics.com

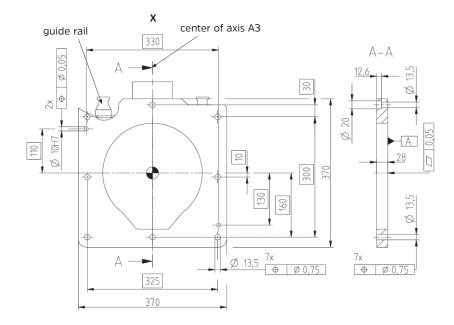
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### LINEAR GANTRY RLP600 TOOL INTERFACE AXIS 3



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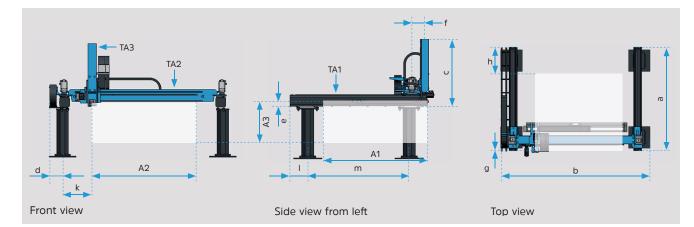
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A company of ARETE COCCHI TECHNOLOGY



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Legend					
<b>A1</b>	Stroke axis 1				
<b>A2</b>	Stroke axis 2				
<b>A3</b>	Stroke axis 3				

TAx Support arm Axis xWS Tool interface A3UK Bottom edgeOK Upper edge

#### Space requirement/footprint

а	Overall length	mm	A1 + 2,160
b	Total width	mm	A2 + 2,650
с	Total height (without stand)	mm	A3 + 925
d	Overhang E-chain	mm	740
е	Lower TA1 to WS	mm	125
f	Center TA2 to WS	mm	530

g	Start TA1 to WS	mm	160
h	End TA1 to WS	mm	925
k	Middle TA1 to WS	mm	865
T.	max. ledge projection TA1	mm	1,250
m	max. distance between uprights	mm	5,000

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