

# LINEAR ROBOT **RL16**

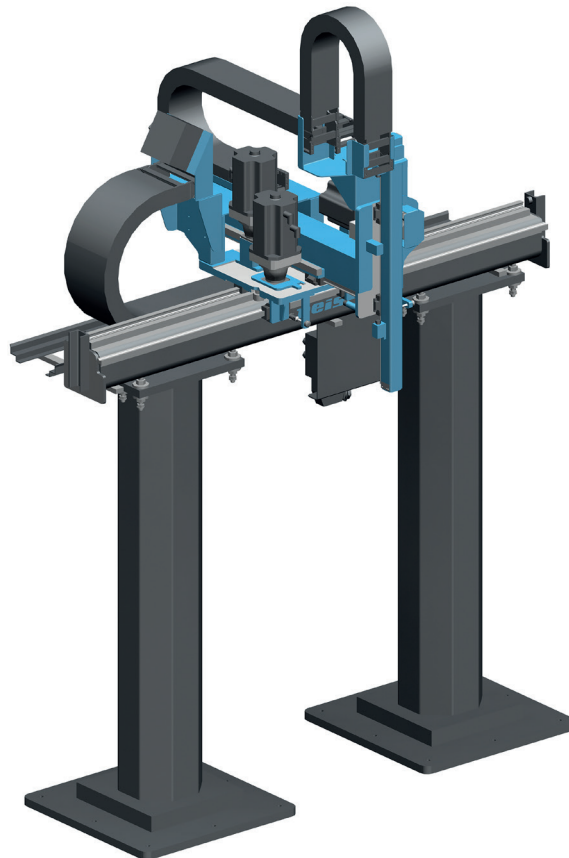
## FOR ENHANCED QUALITY AND PRODUCTIVITY IN LARGE-SCALE WORKSPACES

In its maximum configuration, the **RL16 linear robot** has three cartesian axes and three rotary axes, which are fully synchronized and interpolated servo axes controlled by the robot controller.

The experience gained from a large number of installed handling applications and our expertise as one of the leading providers of intelligent automation solutions for more than five decades have been incorporated into the development of the new **RL16**.

### YOUR BENEFITS

- combined with the very low interference contours of the robot kinematics, this is ideal for interlinking work sequences for loading and unloading, but also for palletizing or transferring
- modular design with workspaces from 0.5 m<sup>3</sup> to 22.5 m<sup>3</sup> make the linear robot a safe investment for your automation system
- state-of-the-art servo drive technologies are used to achieve the best possible dynamics, performance and reliability



### SCOPE OF SUPPLY INCLUDING

- **RL16** with flexible stroke and staggered operating height Basic stroke:  
A1 = 2,000 mm,  
A2 = 500 mm,  
A3 = 500 mm

### OPTIONS

- Wrist axle modules
- Incremental stroke lengths A1 – A3
- Incremental height adjustment of the support columns
- Additional brake A3
- Central lubrication system
- Energy supply
- Adapted to customer specifications
- Extra seals for guiding systems
- Drip protection



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## Technical data

Nominal payload capacity	kg	16
Payload range (depending on stroke A3)	kg	14 to 32
Repeat positioning accuracy	mm	±0.1
Number of axes		3
Work envelope	m <sup>3</sup>	0.5 to 22.5
Medium power consumption	kVA	2.9
Connected load	kVA	4.6
Weight of basic stroke A1 – A3 (without support columns, without load)	kg	approx 373

## Velocities

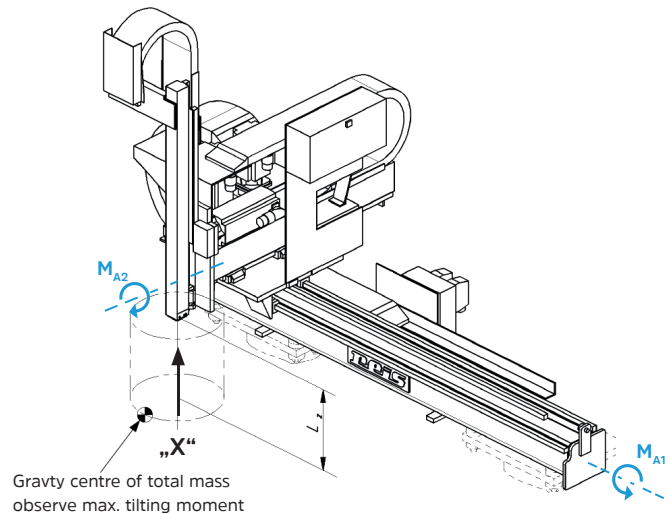
A1	m/s	3
A2	m/s	3
A3	m/s	4

## Strokes

		A1	A2	A3
Basic stroke	mm	2,000	500	500
Max. stroke	mm	15,000	1,000	1,500
Extension steps	mm	1,000	250	250
Extra weight for each upgrade	kg	6	8	4.5

## Support column

Basic size (ø)	mm	345
Basic height	mm	1,750
Maximum height	mm	3,000
Height of extension steps	mm	250
Support column spacing (max.)	mm	5,000
Support arm projection (max.)	mm	1,250



## Table Maximum load A3

Stroke lengths A3 [mm]	Load (max.)	
500	kg	32
750	kg	27.5
1,000	kg	23
1,250	kg	18.5
1,500	kg	14

## Max. lever arm with max. load

L <sub>z</sub>	mm	100
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For further information please contact us under: [sales@reisrobotics.com](mailto:sales@reisrobotics.com)

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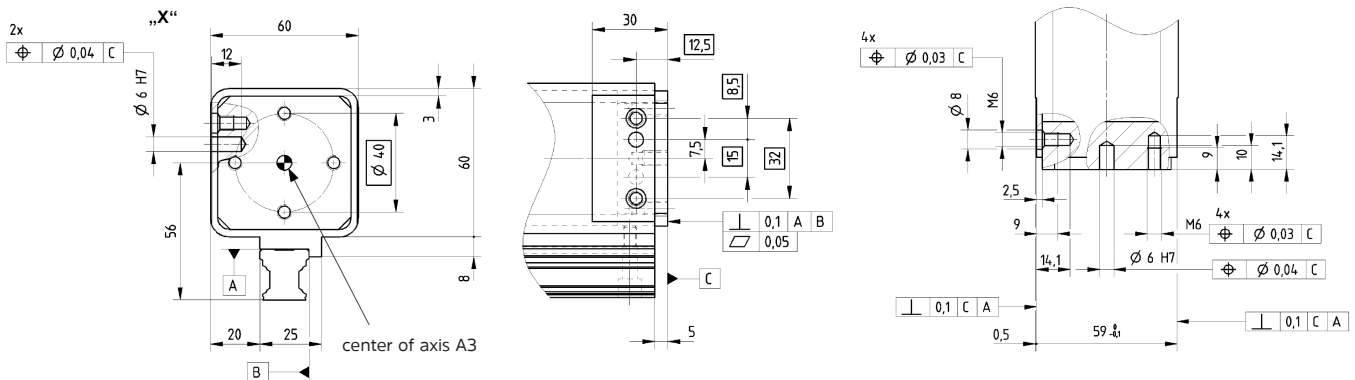
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## ADDITIONAL LOAD

### Additional load on axis A1 and axis A2

Type	stroke lengths A2 / D	Additional load moving along on A1		Additional load moving along on A2	
		max. mass	max. admissible moment around center of support arm A1, generated by L <sub>A1</sub> and L <sub>A2</sub>	max. mass	max. admissible moment around center of support arm A2
	[mm]	L <sub>A1</sub> [kg]	M <sub>A1</sub> [Nm]	L <sub>A2</sub> [kg]	M <sub>A2</sub> [Nm]
RL16	500	33 - L <sub>A2</sub>	116	18	+/- 18
	750	27 - L <sub>A2</sub>	95	12	+/- 12
	1,000	21 - L <sub>A2</sub>	74	6	+/- 6

D = extension of cantilever



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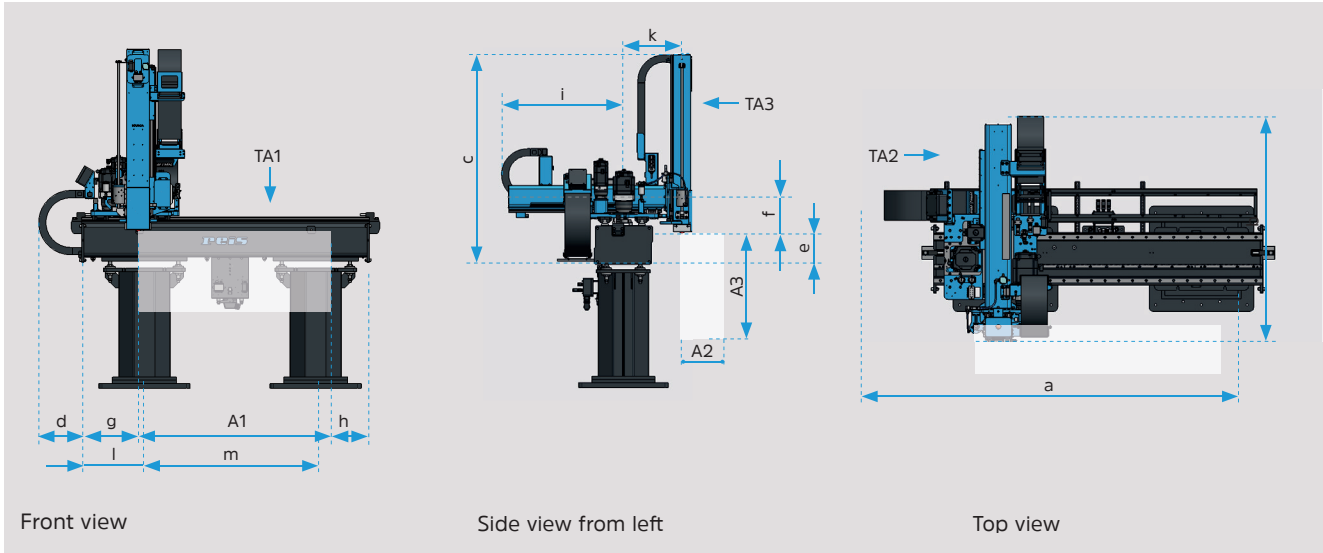
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## WORK ENVELOPE



### Legend

- A1** Stroke axis 1
- A2** Stroke axis 2
- A3** Stroke axis 3

- TAx** Support arm Axis x
- WS** Tool interface A3
- UK** Bottom edge
- OK** Upper edge

### Space requirement/ footprint

<b>a</b>	Overall length	mm	$A1 + 1,055$	<b>h</b>	End TA1 to WS	mm	220
<b>b</b>	Total width	mm	$A2 + 895$	<b>i</b>	Protrusion TA2 Center A1	mm	$A2 + 1,100$
<b>c</b>	Total height (without stand)	mm	$A3 + 1,225$	<b>k</b>	Center TA1 to WS	mm	355
<b>d</b>	Overhang E-chain	mm	515	<b>l</b>	Max. ledge projection TA1	mm	1,250
<b>e</b>	Lower TA1 to WS	mm	150	<b>m</b>	Max. distance between uprights	mm	6,500
<b>f</b>	Center TA2 to WS	mm	165				
<b>g</b>	Start TA1 to WS	mm	280				

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